

Visual Steering Commands and Test Problems to Support Research in Trade Space Exploration*

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AIAA-2008-6085

*12th AIAA/ISSMO Multidisciplinary Analysis and Optimization Conference
10-12 September 2008, Victoria, British Columbia, Canada*

* This work is funded by the National Science Foundation under Grant # CMMI-0620948.



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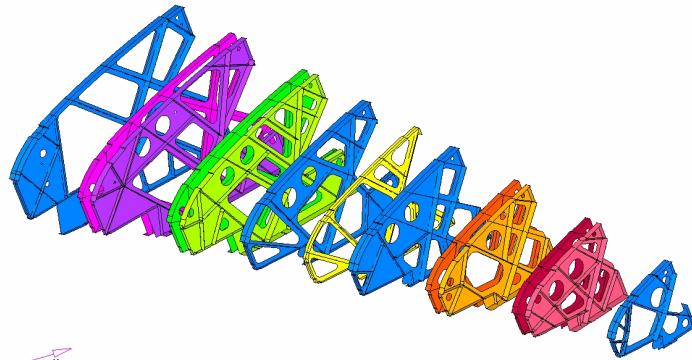
Overview of Presentation

- Trade Space Exploration
 - Motivation for the work
 - Optimization vs. exploration
- ARL Trade Space Visualizer (ATSV)
 - Multidimensional data visualization
 - Visual Steering Commands
- Suite of Test Problems
 - Complex engineered systems for land, sea, air, and space
- Sample Results
- Closing Remarks

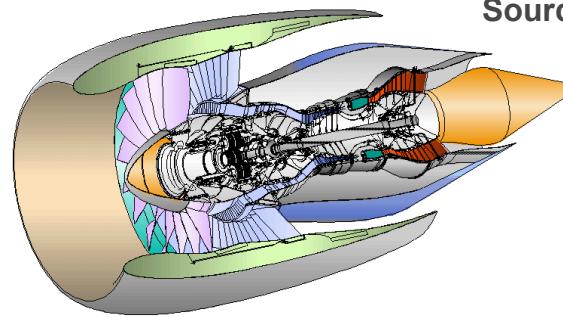


Modeling, Analysis, and Simulation

- Recent advances in computing power and speed allow designers to simulate and evaluate thousands, if not millions, of design alternatives more cheaply and quickly than ever before
- These advancements provide new opportunities to revolutionize trade space exploration for the design of complex systems



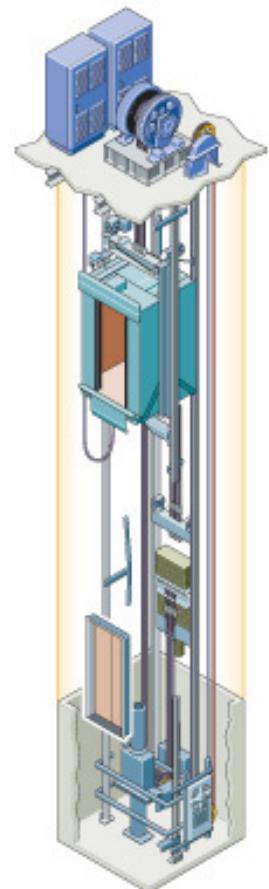
Source: Altair Engineering



Source: Trevor Bailey, UTRC



Source: Fiat



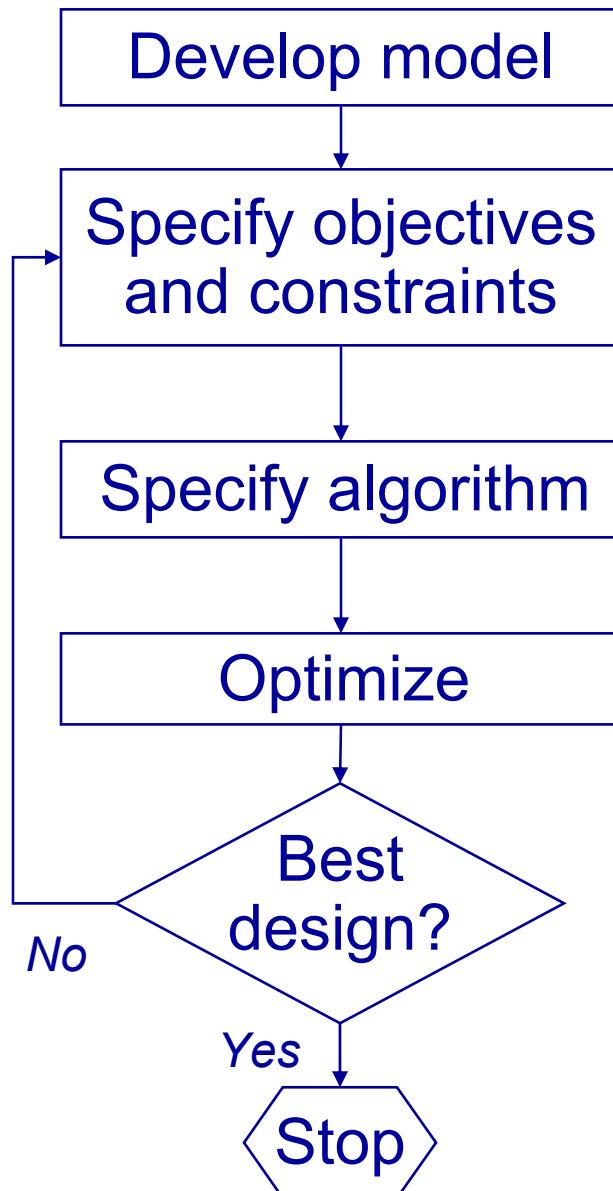
Source:
www.otis.com

Which is the best design?

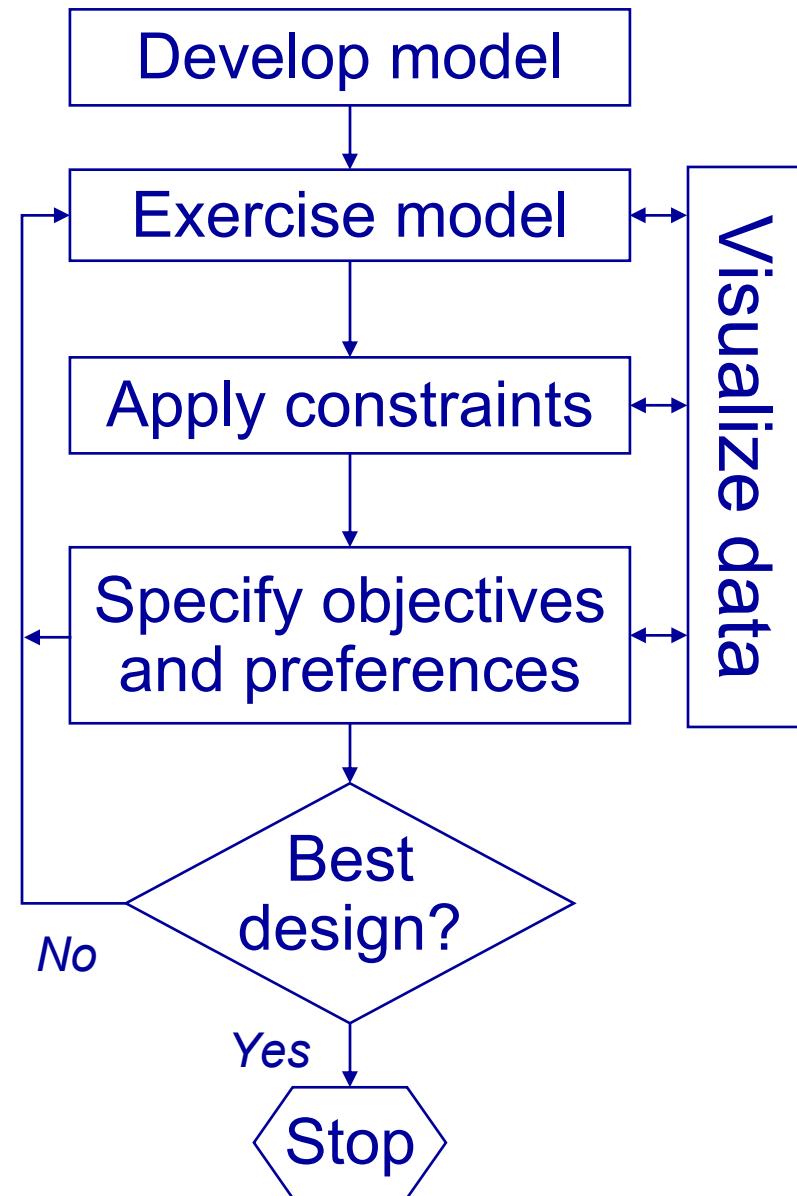
| A | B | C | D | E | F | G | H | I | J | K | Mass | ConVio | Obj1 | Obj2 | Obj3 | Obj4 | Obj5 |
|----------|----------|----------|----------|----------|----------|----------|---|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|
| 0.624649 | 0.754049 | 0.876689 | 0.343205 | 0.212124 | 0.932773 | 0.57122 | 3 | 0.696767 | 0.520956 | 0.061564 | 1.065553 | 85.3757 | 1.062015 | 0.988355 | 0.975157 | 0.949053 | 1.015516 |
| 0.060985 | 0.157698 | 0.100316 | 0.147226 | 0.723355 | 0.954276 | 0.18665 | 5 | 0.147579 | 0.594634 | 0.546073 | 0.869276 | 280.5069 | 0.821385 | 1.062017 | 0.984424 | 1.02363 | 0.845335 |
| 0.79029 | 0.753857 | 0.374672 | 0.23151 | 0.568749 | 0.966105 | 0.926726 | 5 | 0.861844 | 0.206967 | 0.152046 | 1.087959 | 162.1251 | 1.025622 | 1.009793 | 0.935661 | 0.962082 | 0.950406 |
| 0.386879 | 0.088587 | 0.001015 | 0.89747 | 0.369036 | 0.575776 | 0.907945 | 1 | 0.425441 | 0.129497 | 0.930208 | 0.897125 | 0 | 1.27605 | 1.128511 | 0.925916 | 1.095028 | 0.727479 |
| 0.00745 | 0.664116 | 0.161524 | 0.613925 | 0.45661 | 0.734871 | 0.954844 | 6 | 0.944188 | 0.415194 | 0.177407 | 0.861764 | 418.1174 | 0.605767 | 0.90523 | 0.961853 | 0.973201 | 0.965639 |
| 0.995651 | 0.743935 | 0.320403 | 0.090145 | 0.48886 | 0.393002 | 0.876449 | 4 | 0.828249 | 0.673172 | 0.795096 | 1.183174 | 297.2661 | 0.918957 | 0.864233 | 0.994303 | 1.079725 | 1.043906 |
| 0.328119 | 0.856472 | 0.01425 | 0.842507 | 0.451588 | 0.130799 | 0.974695 | 1 | 0.758214 | 0.163655 | 0.641987 | 0.858018 | 0 | 1.210881 | 1.153077 | 0.930213 | 1.064094 | 0.973342 |
| 0.435725 | 0.714144 | 0.590085 | 0.488513 | 0.195516 | 0.353903 | 0.095564 | 6 | 0.800199 | 0.121332 | 0.74331 | 0.980696 | 84.54371 | 0.69339 | 0.882991 | 0.924889 | 1.072899 | 0.920315 |
| 0.140543 | 0.619531 | 0.286546 | 0.547551 | 0.700957 | 0.820492 | 0.122013 | 3 | 0.544486 | 0.027115 | 0.396837 | 0.81166 | 75.67446 | 0.798757 | 1.070938 | 0.913038 | 1.004613 | 0.871374 |
| 0.053287 | 0.967234 | 0.027151 | 0.285497 | 0.11165 | 0.493894 | 0.312822 | 2 | 0.834215 | 0.607056 | 0.965347 | 0.856679 | 190.3453 | 0.994475 | 1.086928 | 0.985987 | 1.103027 | 1.099647 |
| 0.016589 | 0.081024 | 0.077573 | 0.970116 | 0.236366 | 0.197258 | 0.299823 | 4 | 0.897914 | 0.996856 | 0.145421 | 0.899552 | 314.8964 | 0.689412 | 0.930108 | 1.035018 | 0.984929 | 0.904823 |
| 0.339073 | 0.804103 | 0.194134 | 0.595187 | 0.893329 | 0.173013 | 0.599763 | 3 | 0.682347 | 0.211061 | 0.433533 | 0.936625 | 0 | 0.92971 | 1.026089 | 0.936176 | 1.030417 | 0.966879 |
| 0.807105 | 0.355682 | 0.698499 | 0.347406 | 0.147357 | 0.833227 | 0.239664 | 5 | 0.180274 | 0.339442 | 0.126236 | 1.107651 | 142.5201 | 1.046443 | 1.001878 | 0.952325 | 0.962201 | 0.854032 |
| 0.461698 | 0.808808 | 0.448971 | 0.555792 | 0.308602 | 0.078053 | 0.713475 | 1 | 0.804761 | 0.911746 | 0.592818 | 1.005789 | 0 | 1.455601 | 1.070847 | 1.024313 | 1.058098 | 1.113506 |
| 0.893653 | 0.178552 | 0.302888 | 0.772328 | 0.540938 | 0.210228 | 0.633615 | 2 | 0.242687 | 0.707757 | 0.370249 | 1.158954 | 197.4329 | 1.352289 | 0.997158 | 0.998654 | 1.019435 | 0.875256 |
| 0.593384 | 0.607663 | 0.564 | 0.670026 | 0.432504 | 0.034409 | 0.42949 | 1 | 0.765861 | 0.284269 | 0.456763 | 0.990321 | 25.37839 | 1.406297 | 1.099572 | 0.945385 | 1.038328 | 0.920959 |
| 0.011539 | 0.850963 | 0.099594 | 0.619666 | 0.527305 | 0.132944 | 0.404533 | 4 | 0.163654 | 5.26E-04 | 0.410111 | 0.78425 | 153.0766 | 0.593367 | 0.965405 | 0.909694 | 1.028025 | 0.937833 |
| 0.917945 | 0.354331 | 0.360415 | 0.949183 | 0.654889 | 0.883763 | 0.858601 | 1 | 0.113017 | 0.578143 | 0.005751 | 1.111352 | 342.9728 | 1.58323 | 1.057398 | 0.98235 | 0.941924 | 0.903065 |
| 0.629985 | 0.367476 | 0.030701 | 0.823217 | 0.751167 | 0.709767 | 0.134882 | 2 | 0.418778 | 0.074323 | 0.700772 | 1.010063 | 76.0458 | 1.163879 | 1.05292 | 0.918976 | 1.055243 | 0.802774 |
| 0.052335 | 0.607279 | 0.051817 | 0.635463 | 0.083765 | 0.384859 | 0.553443 | 3 | 0.246573 | 0.031671 | 0.894493 | 0.793414 | 128.5993 | 0.786491 | 1.064864 | 0.913611 | 1.095411 | 0.868508 |
| 0.26956 | 0.542476 | 0.324995 | 0.205405 | 0.925943 | 0.712346 | 0.350751 | 1 | 0.603615 | 0.889306 | 0.925155 | 0.930262 | 33.28389 | 1.350634 | 1.090706 | 1.02149 | 1.090002 | 1.026037 |
| 0.113861 | 0.023778 | 0.544848 | 0.464351 | 0.032314 | 0.264167 | 0.608364 | 2 | 0.312497 | 0.737143 | 0.487076 | 0.884893 | 155.3781 | 1.022127 | 1.085544 | 1.00235 | 1.0359 | 0.833215 |
| 0.790459 | 0.561394 | 0.075355 | 0.0309 | 0.604376 | 0.881564 | 0.38648 | 2 | 0.126824 | 0.425601 | 0.840445 | 1.102166 | 155.5182 | 1.286927 | 1.01118 | 0.963162 | 1.071595 | 0.935852 |
| 0.925059 | 0.529395 | 0.398783 | 0.664759 | 0.711469 | 0.374232 | 0.432993 | 1 | 0.835886 | 0.999606 | 0.914148 | 1.164511 | 175.0352 | 1.718627 | 1.002366 | 1.035364 | 1.098793 | 1.044821 |
| 0.492116 | 0.483754 | 0.11385 | 0.268324 | 0.139095 | 0.327651 | 0.775126 | 6 | 0.621833 | 0.201755 | 0.208674 | 1.00229 | 58.42594 | 0.706126 | 0.884241 | 0.935005 | 0.990701 | 0.865333 |
| 0.714184 | 0.664542 | 0.11446 | 0.017024 | 0.642118 | 0.80771 | 0.881159 | 1 | 0.732738 | 0.829098 | 0.932108 | 1.097304 | 48.51039 | 1.606783 | 1.02979 | 1.013917 | 1.088121 | 1.051521 |
| 0.118918 | 0.017629 | 0.924812 | 0.061686 | 0.046908 | 0.643381 | 0.633561 | 4 | 0.393291 | 0.268319 | 0.75947 | 0.838012 | 88.64945 | 0.640139 | 0.944516 | 0.943378 | 1.066418 | 0.734174 |
| 0.255594 | 0.214463 | 0.598632 | 0.714721 | 0.033801 | 0.594344 | 0.049352 | 1 | 0.324555 | 0.549029 | 0.104542 | 0.887475 | 52.14604 | 1.250313 | 1.145112 | 0.978688 | 0.966251 | 0.853539 |
| 0.007185 | 0.837426 | 0.285541 | 0.180206 | 0.001931 | 0.242974 | 0.695136 | 3 | 0.981152 | 0.061027 | 0.13798 | 0.787168 | 176.7205 | 0.771164 | 1.084224 | 0.917304 | 0.982354 | 0.946158 |
| 0.193436 | 0.59333 | 0.575079 | 0.123012 | 0.805085 | 0.819283 | 0.574159 | 2 | 0.184029 | 0.347939 | 0.975802 | 0.857098 | 43.93821 | 0.990329 | 1.09325 | 0.953393 | 1.094545 | 0.929693 |
| 0.928198 | 0.389419 | 0.115175 | 0.613135 | 0.762898 | 0.396141 | 0.017512 | 4 | 0.304104 | 0.677509 | 0.91514 | 1.168977 | 234.6986 | 0.909056 | 0.865166 | 0.994849 | 1.098267 | 0.934562 |
| 0.222651 | 0.467807 | 0.951467 | 0.56811 | 0.520733 | 0.053605 | 0.928277 | 3 | 0.88145 | 0.383813 | 0.740516 | 0.901219 | 26.40954 | 0.90048 | 1.025809 | 0.957906 | 1.08179 | 0.898092 |
| 0.811201 | 0.133245 | 0.378015 | 0.68068 | 0.872205 | 0.49669 | 0.520425 | 5 | 0.0733 | 0.350462 | 0.452241 | 1.109873 | 81.78877 | 1.053422 | 0.994934 | 0.953711 | 1.023271 | 0.787145 |
| 0.423361 | 0.642631 | 0.712732 | 0.891548 | 0.734774 | 0.993534 | 0.88727 | 1 | 0.784954 | 0.059616 | 0.47451 | 0.896664 | 13.57533 | 1.260446 | 1.145038 | 0.917126 | 1.011299 | 0.885291 |
| 0.632001 | 0.461677 | 0.108156 | 0.912385 | 0.016923 | 0.345369 | 0.191936 | 4 | 0.336829 | 0.668814 | 0.53677 | 1.08797 | 0 | 0.83955 | 0.888839 | 0.993755 | 1.041094 | 0.955231 |
| 0.873147 | 0.508414 | 0.360317 | 0.405932 | 0.222425 | 0.053973 | 0.93098 | 4 | 0.314139 | 0.515362 | 0.294384 | 1.137171 | 214.504 | 0.874249 | 0.884942 | 0.974453 | 1.012508 | 0.937973 |
| 0.885007 | 0.781797 | 0.714749 | 0.35023 | 0.385047 | 0.487096 | 0.690444 | 4 | 0.458081 | 0.539834 | 0.562325 | 1.142733 | 220.8034 | 0.882082 | 0.87889 | 0.977531 | 1.040661 | 1.028056 |
| 0.036627 | 0.355758 | 0.005696 | 0.757361 | 0.319842 | 0.561181 | 0.406254 | 2 | 0.751786 | 0.880089 | 0.388129 | 0.8844 | 257.4996 | 1.022278 | 1.084719 | 1.020331 | 1.011313 | 0.966064 |
| 0.621134 | 0.26736 | 0.115896 | 0.698524 | 0.324068 | 0.943496 | 0.557317 | 2 | 0.1309 | 0.522604 | 0.896984 | 1.0619 | 0 | 1.241092 | 1.020734 | 0.975364 | 1.07845 | 0.864514 |
| 0.493668 | 0.564122 | 0.60814 | 0.117899 | 0.772721 | 0.605714 | 0.547454 | 4 | 0.819652 | 0.090314 | 0.471688 | 0.958514 | 30.04471 | 0.730484 | 0.927495 | 0.920988 | 1.022904 | 0.867237 |
| 0.273529 | 0.548112 | 0.988656 | 0.882654 | 0.25439 | 0.246603 | 0.397196 | 5 | 0.288987 | 0.436134 | 0.337391 | 0.927578 | 95.88232 | 0.874011 | 1.051251 | 0.964487 | 1.013204 | 0.933903 |
| 0.149734 | 0.317481 | 0.19274 | 0.388216 | 0.898963 | 0.313182 | 0.953739 | 5 | 0.388612 | 0.048113 | 0.646596 | 0.82531 | 170.1594 | 0.773724 | 1.085413 | 0.915679 | 1.059146 | 0.781797 |
| 0.653178 | 0.273579 | 0.629722 | 0.666803 | 0.995326 | 0.352516 | 0.104895 | 4 | 0.263001 | 0.49329 | 0.815411 | 1.071509 | 17.21235 | 0.827531 | 0.890659 | 0.971677 | 1.084137 | 0.860374 |
| 0.472799 | 0.156696 | 0.041151 | 0.345065 | 0.351738 | 0.483427 | 0.93028 | 6 | 0.766748 | 0.388929 | 0.282111 | 1.020344 | 56.32071 | 0.72098 | 0.878103 | 0.958549 | 0.997266 | 0.802407 |
| 0.907584 | 0.818911 | 0.940492 | 0.757801 | 0.051914 | 0.137225 | 0.701082 | 5 | 0.757653 | 0.958448 | 0.353178 | 1.205011 | 44.55034 | 1.155917 | 0.958121 | 1.030187 | 1.019052 | 1.126324 |
| 0.861104 | 0.686593 | 0.484355 | 0.998615 | 0.749554 | 0.084413 | 0.891419 | 1 | 0.204854 | 0.612706 | 0.701557 | 1.103201 | 185.3407 | 1.598347 | 1.040067 | 0.986697 | 1.074784 | 1.013548 |
| 0.160185 | 0.382135 | 0.774365 | 0.092991 | 0.177952 | 0.221956 | 0.016188 | 3 | 0.723065 | 0.144779 | 0.924658 | 0.829475 | 63.8893 | 0.825459 | 1.04983 | 0.927839 | 1.105154 | 0.821929 |
| 0.031606 | 0.779571 | 0.563722 | 0.351247 | 0.772206 | 0.162459 | 0.396974 | 4 | 0.866714 | 0.130713 | 0.28886 | 0.803458 | 141.0366 | 0.6083 | | | | |

Shifting to a Better Paradigm?

Design by Optimization



Trade Space Exploration



ARL Trade Space Visualizer (ATSV)

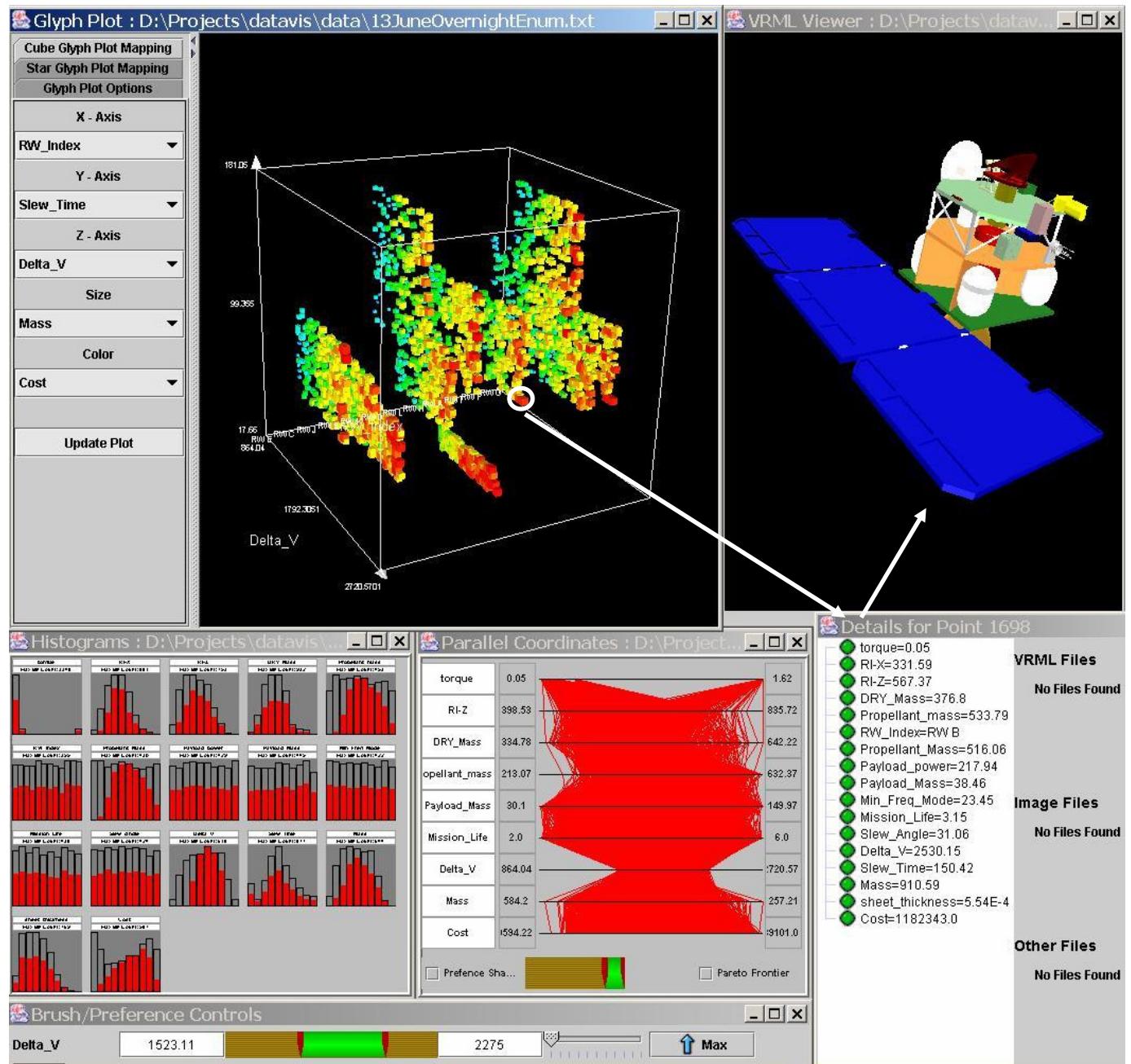
Multi-dimensional data visualization:

- ❑ Glyph plots
- ❑ Histogram plots
- ❑ Parallel coordinates
- ❑ Scatter matrices
- ❑ Brushing
- ❑ Linked views

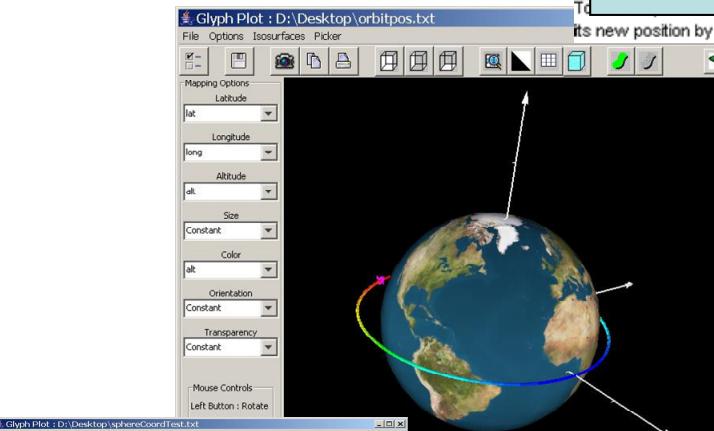
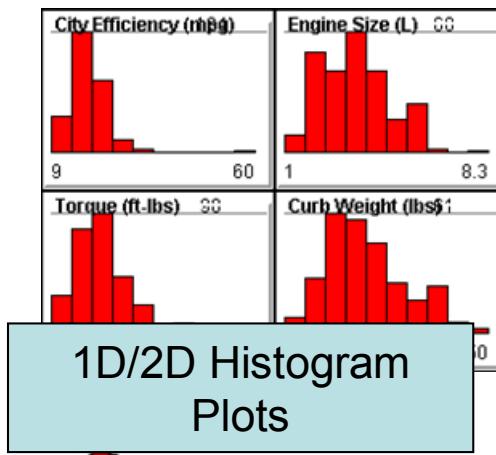
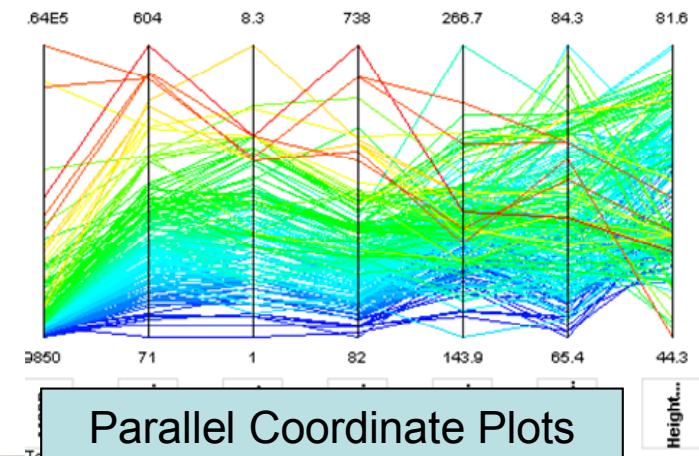
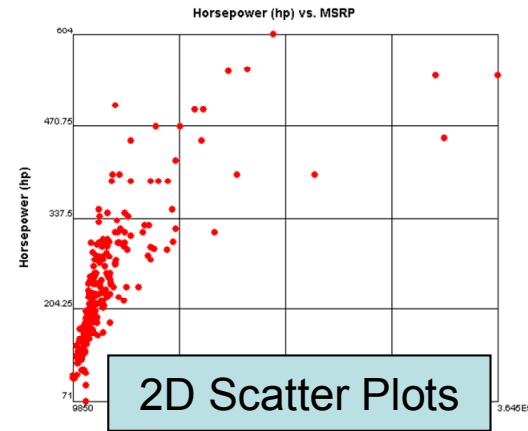
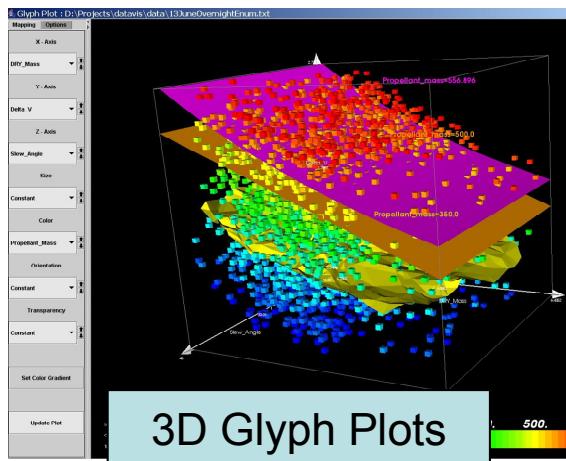
Display multiple plots simultaneously

Interrogate specific design points

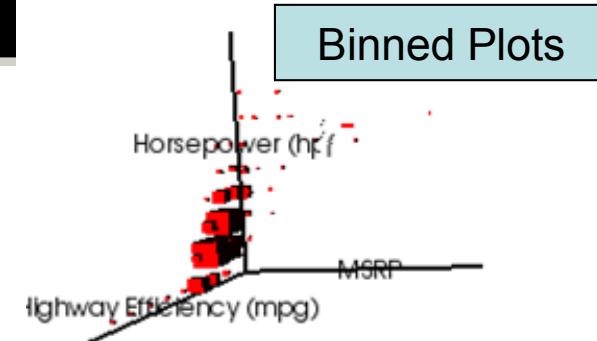
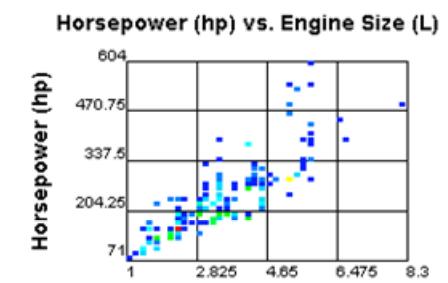
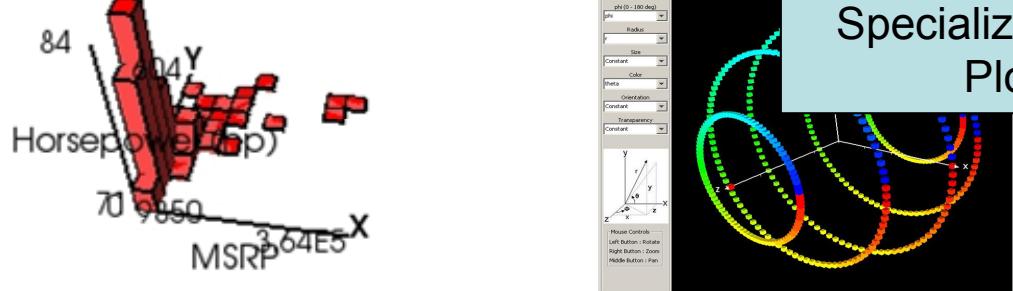
Interactively apply preferences and constraints



Multi-Dimensional Data Visualization



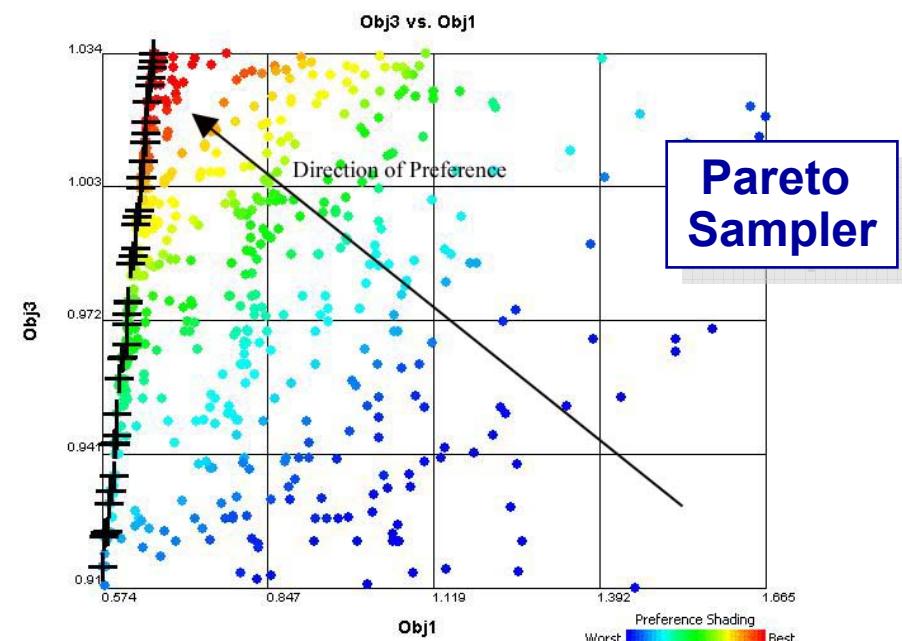
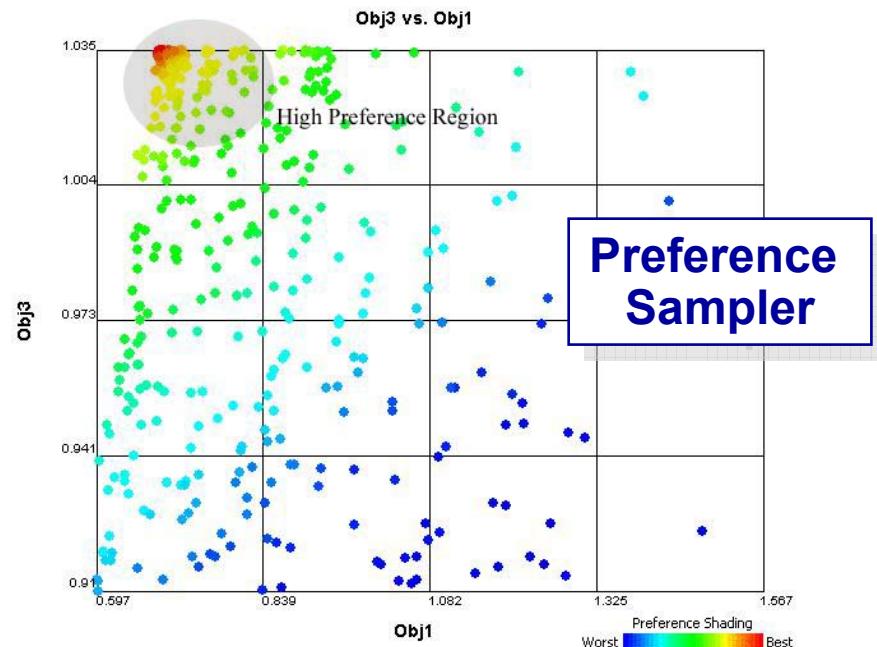
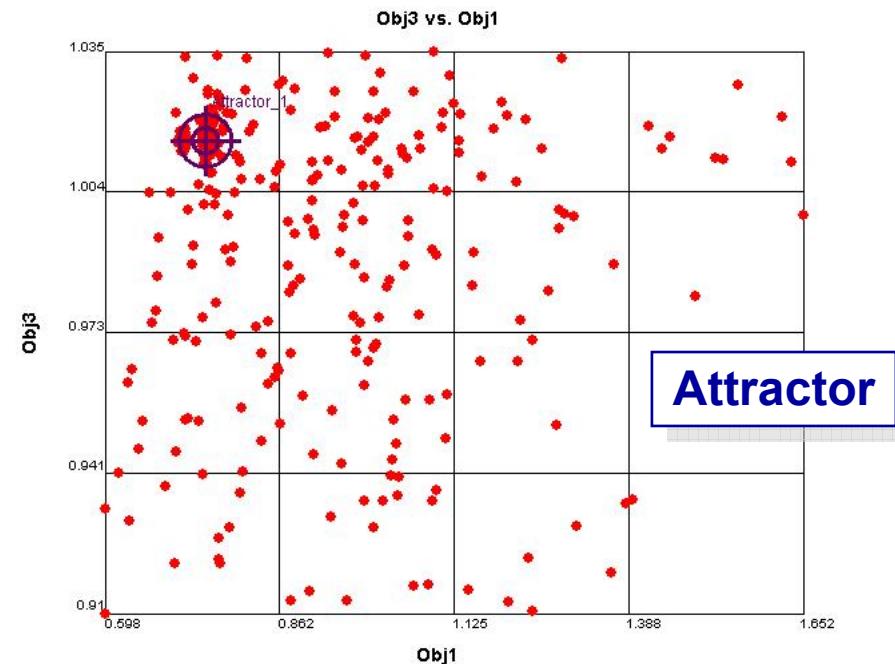
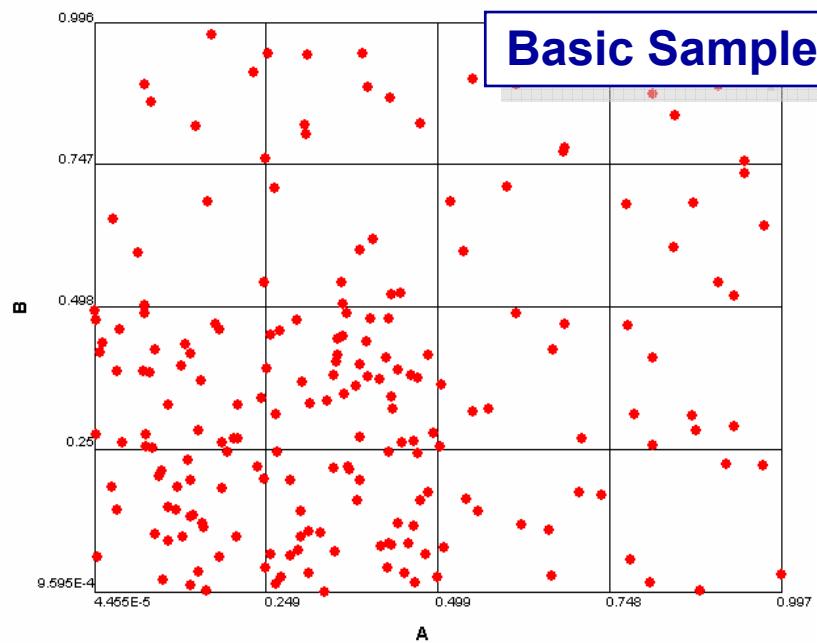
Specialized Glyph Plots



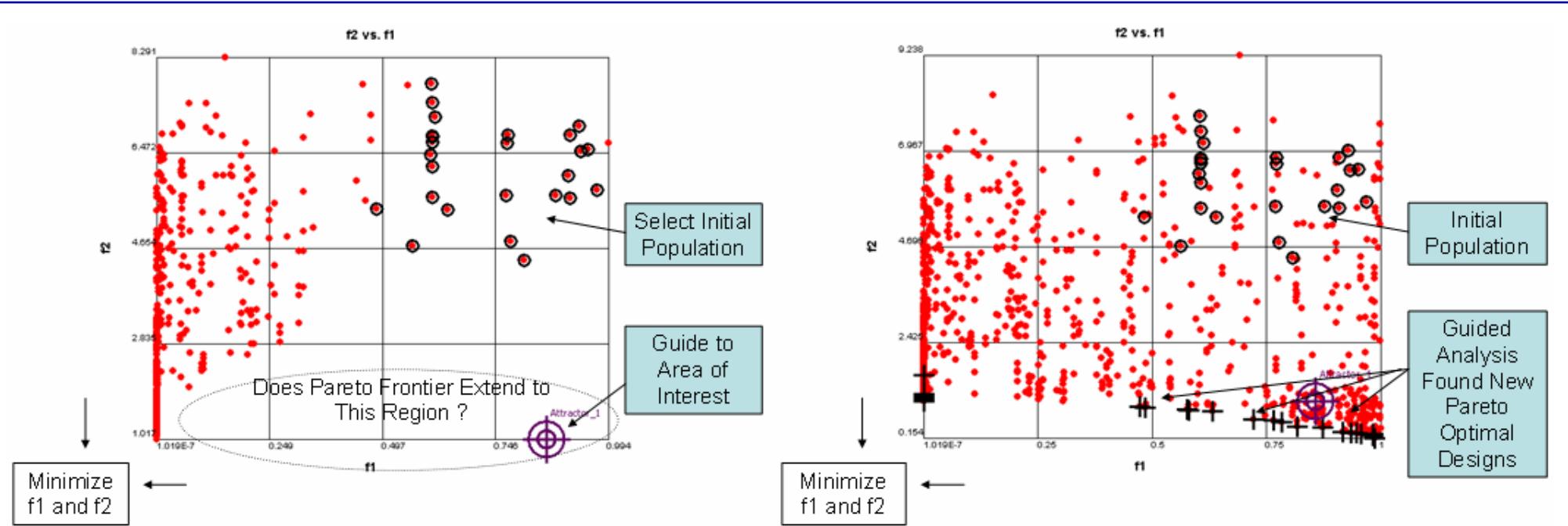
Binned Plots

Visual Steering Commands

Refer to: (ASME DETC2007-34684)



Guided Pareto Sampling

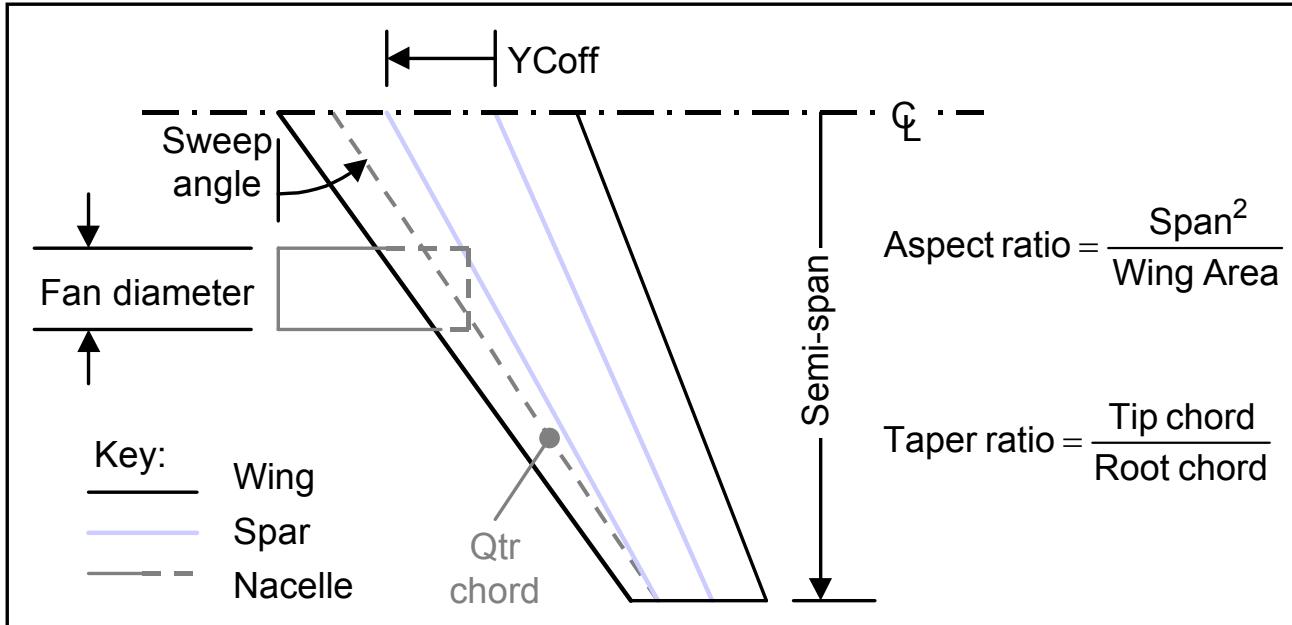


- Guided Pareto Sampler allows users to:
 - Select specific points within any data visualization window and use them to seed the initial generation for Pareto search
 - “Guide” Pareto search algorithms to regions of interest using Attractor icons
 - Start, pause, and stop the search at any time to change initial generation, guided search direction, modify formulation, etc.

Aircraft Wing Sizing Problem

Design variables:

1. Semi-span
2. Aspect ratio
3. Sweep angle
4. Taper ratio
5. Sparbox root chord
6. Fan diameter



Bounds: $x_i^{\text{lower}} \leq x_i \leq x_i^{\text{upper}}$

Problem Statement:

Minimize: Cost

Maximize: Range

subject to: Range ≥ 0.589

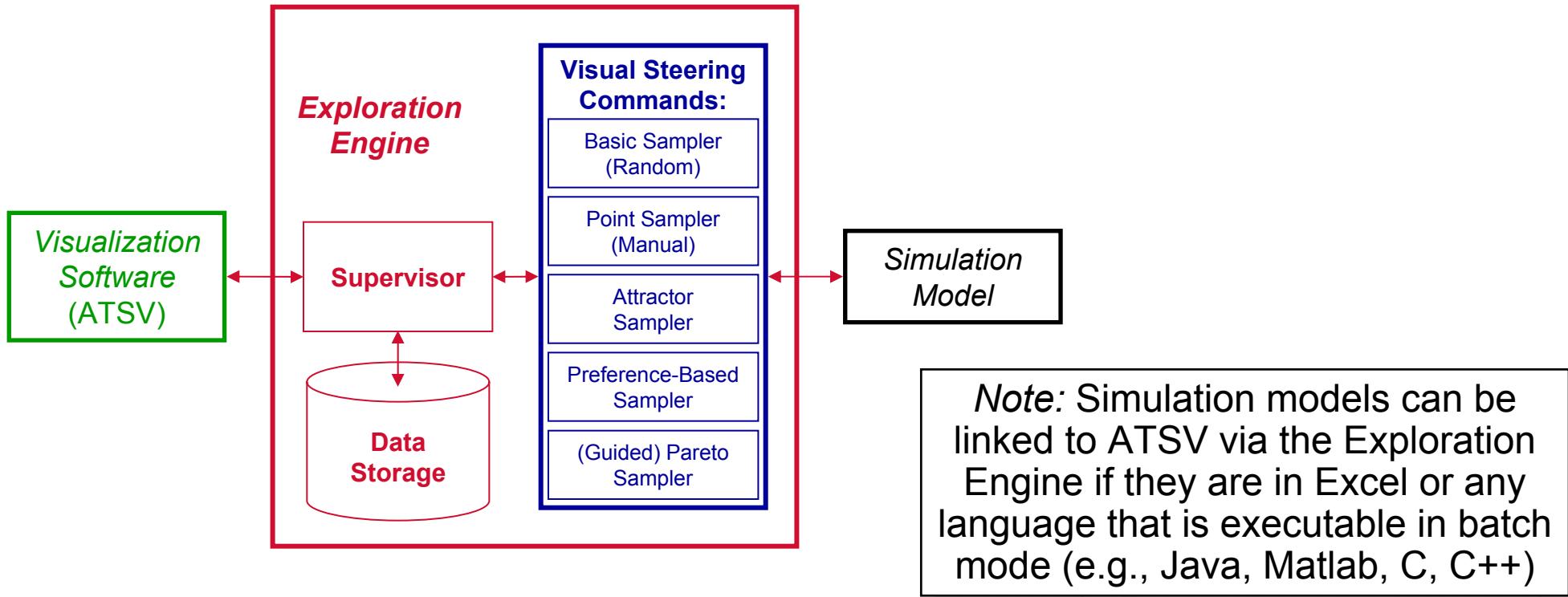
Buffet altitude ≥ 0.603

Takeoff field length ≤ 0.377

Values were obtained from
2nd-order response surface
models developed from a
243 point orthogonal array

Implementation with ATSV

- Visual Steering Commands are handled independently of ATSV using an Exploration Engine:
 - user specifies Visual Steering Commands within ATSV
 - Exploration Engine invokes simulation model, stores new sample data, and updates ATSV displays
 - message passing protocol handles all communication



Problem Test Suite

- In order to test algorithmic developments and perform experimental user studies, we have created a suite of test problems that vary in size, complexity, etc.

| Domain | Problem | Inputs | Objectives | Constraints |
|--------|----------------------------------|--------|------------------------|-------------|
| Land | Vehicle Configuration Model | 11 | 5 | 2 |
| Sea | Conceptual Ship Design | 6 | 3 | 9 |
| Air | Aircraft Wing Sizing | 6 | 2 | 3 |
| Space | Space Shuttle External Fuel Tank | 5 | 1 System & 4 Subsystem | 4 |

- Problems are representative of conceptual design of complex engineered systems in the four domains



Vehicle Configuration Model

Refer to: (ASME
DETC2007-34684)

- We used a vehicle configuration model that evaluates the technical feasibility of new vehicle concepts*

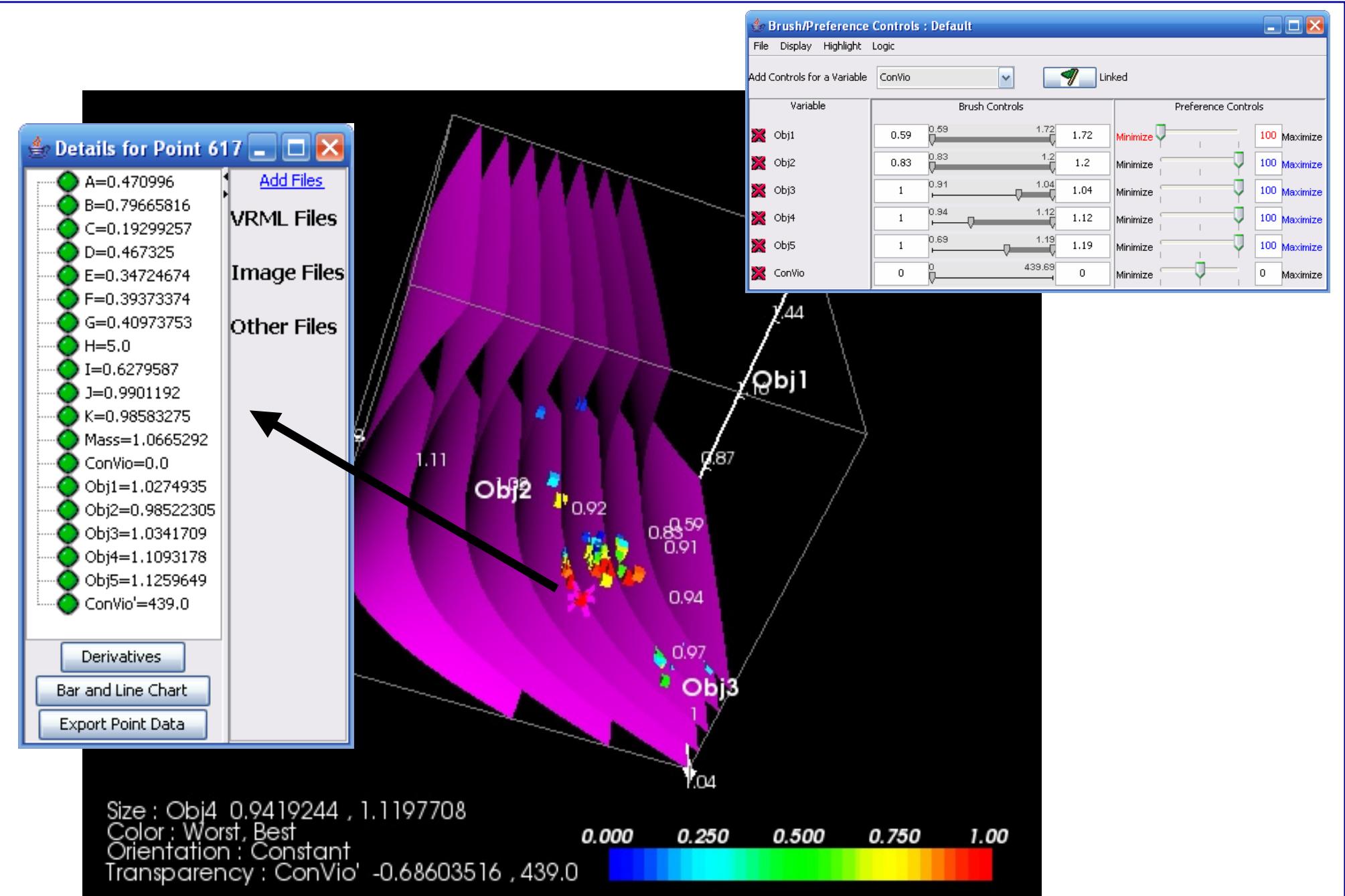
- Inputs: 11
 - External dimensions
 - Occupant positions
 - Power train (discrete)
- Objectives: 5
 - Acceleration
 - Fuel economy
 - Interior accommodation
- Vehicle mass
- Total constraint violation

* Ferguson, Lewis, and Donndelinger, et al.
2004, 2005 & 2006 MAO & DETC papers

| Model Inputs | | |
|---------------|--------------------------|------------------------------|
| Variable | Lower Bound | Upper Bound |
| A | 0 | 1 |
| B | 0 | 1 |
| C | 0 | 1 |
| D | 0 | 1 |
| E | 0 | 1 |
| F | 0 | 1 |
| G | 0 | 1 |
| H | 1,2,3,4,5, or 6 | |
| I | 0 | 1 |
| J | 0 | 1 |
| K | 0 | 1 |
| Model Outputs | | |
| $ConVio$ | $0 \rightarrow$ feasible | $> 0 \rightarrow$ infeasible |
| $Mass$ | Baseline = 1 | Defines weight class |
| $Obj1$ | Baseline = 1 | Smaller is better |
| $Obj2$ | Baseline = 1 | Larger is better |
| $Obj3$ | Baseline = 1 | Larger is better |
| $Obj4$ | Baseline = 1 | Larger is better |
| $Obj5$ | Baseline = 1 | Larger is better |



Final Glyph Plot with Weight Classes



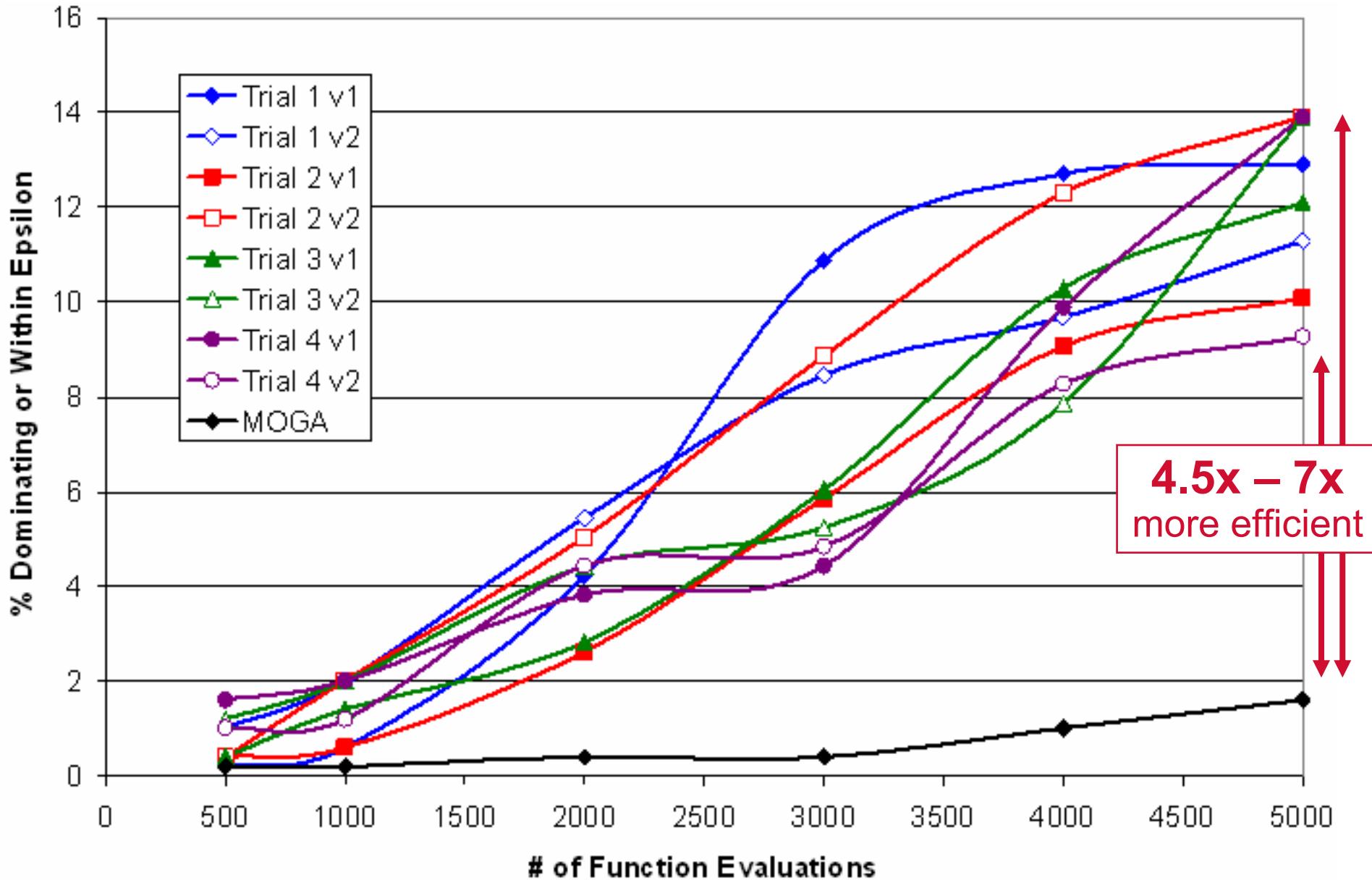
Quantifying Benefits of Our Approach

Refer to: (ASME
DETC2008-49681)

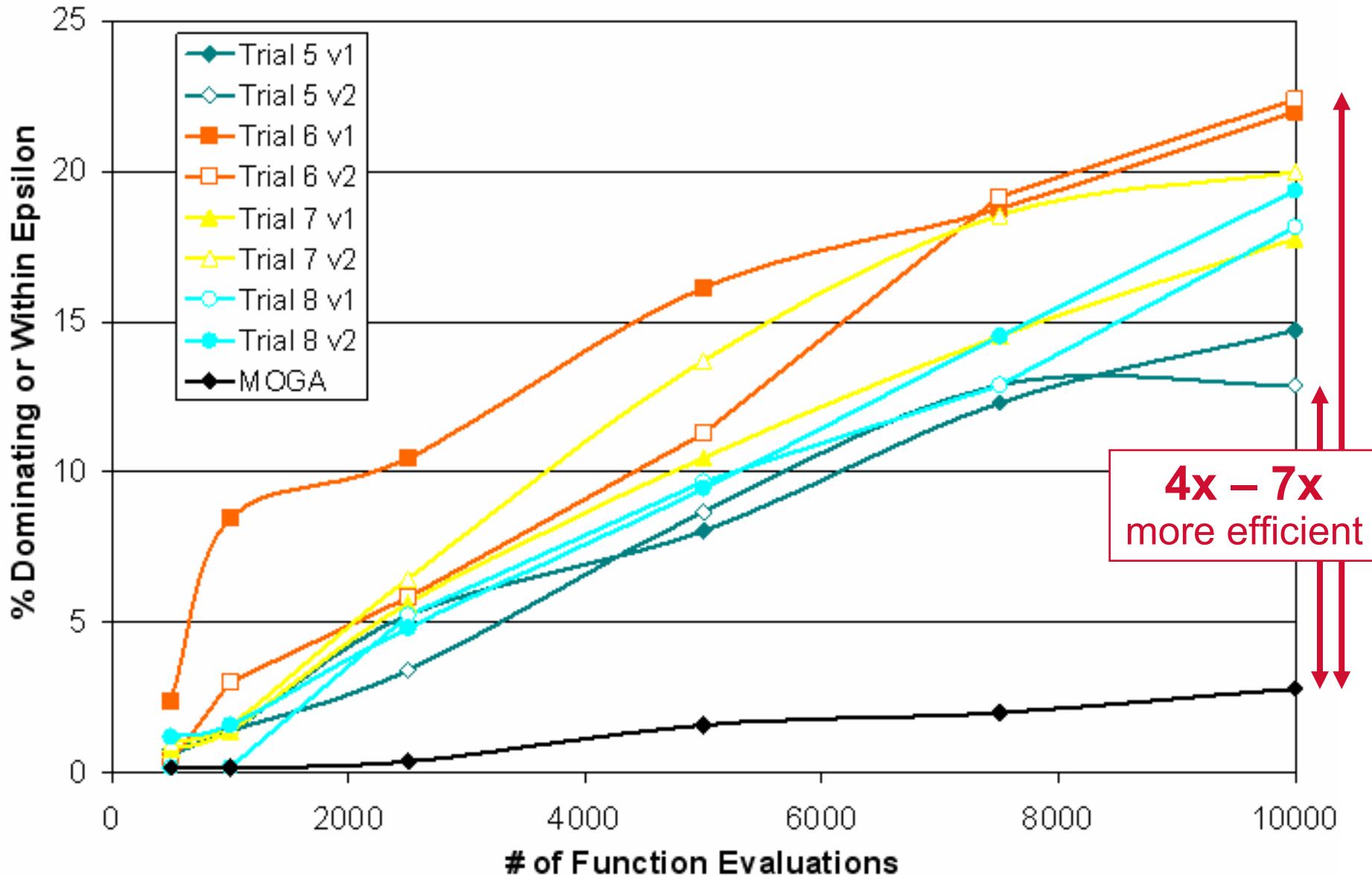
- Research Objective:
 - Provide empirical evidence of the benefits of interactive visualization-based strategies that can support design optimization and decision-making
- Experimental Study:
 - Experimentally assess the effectiveness of user-guided visual steering in locating good (Pareto) solutions
- Experimental Set-Up:
 - Vehicle configuration model (11 inputs, 5 objectives)
 - Two users, 8 trials (4 w/5,000 fcn evals; 4 w/10,000 fcn evals)
 - Benchmark: 80,000 function evaluations in MOGA
 - Compare resulting Pareto fronts using ε -performance metric



Evolution of Solutions for Trials 1-4 (5,000 pts)



Evolution of Solutions for Trials 5-8 (10,000 pts)

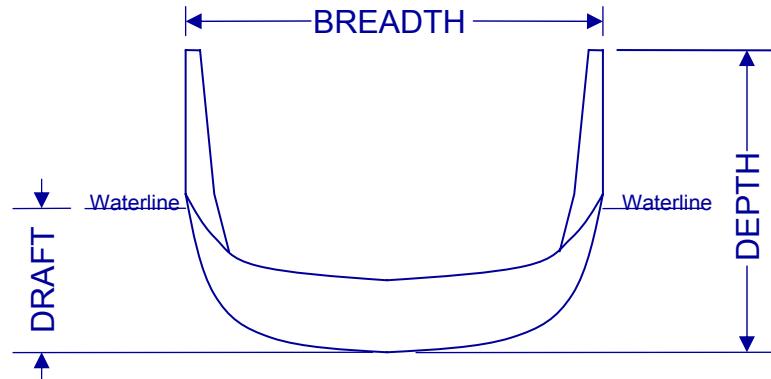


Conceptual Ship Design

Analytical model* approximates a family of bulk carriers with deadweight between 3,000-50,000 tons and speeds of 14-18 knots

Design Variables:

1. Length, $150 \leq L \leq 274.32$
2. Beam, $21 \leq B \leq 32.31$
3. Depth, $12 \leq D \leq 25$
4. Draft, $9.5 \leq T \leq 11.71$
5. Block Coefficient, $0.63 \leq C_B \leq 0.75$
6. Speed, $14 \leq V_k \leq 18$

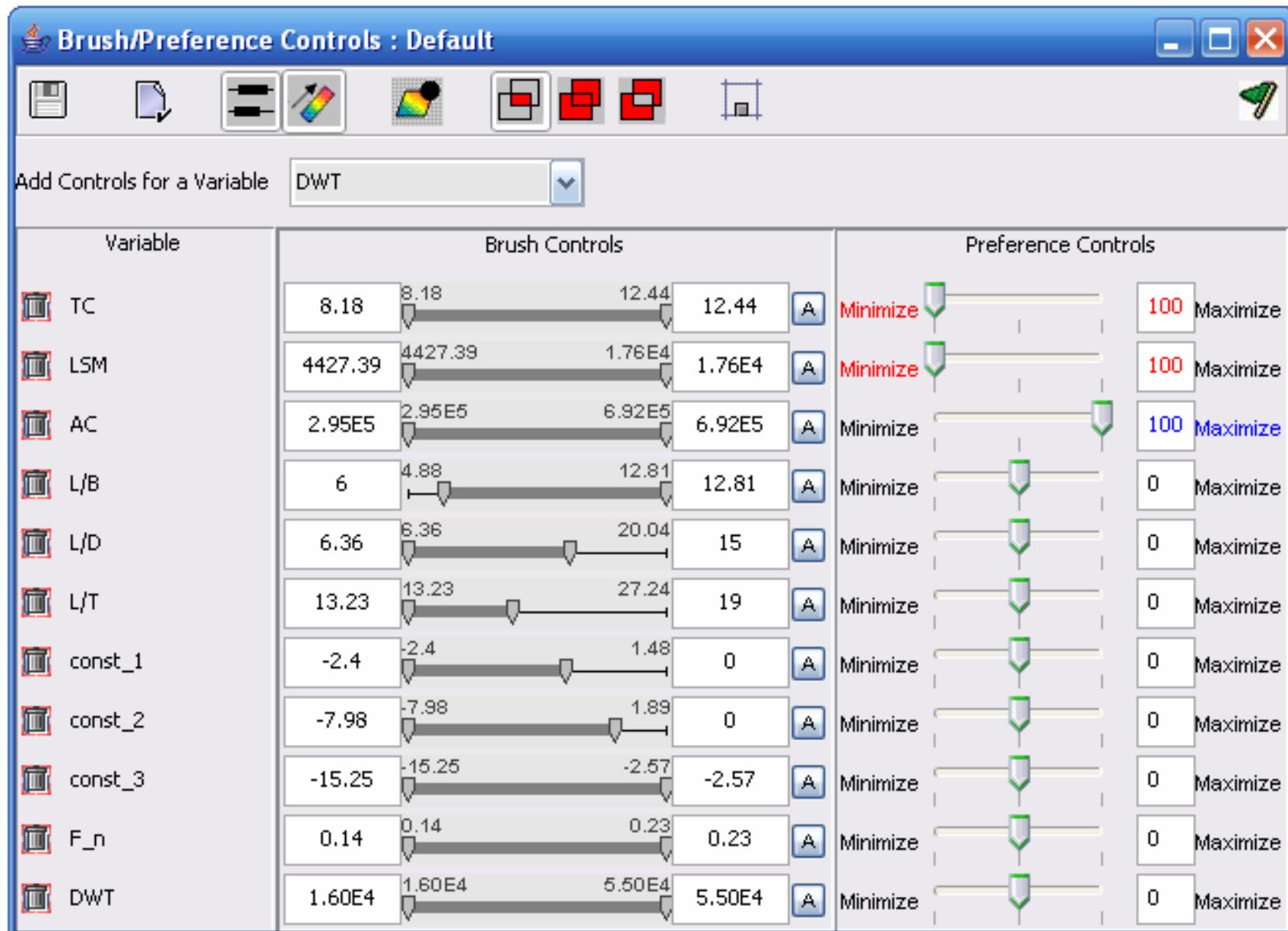


Problem Statement:

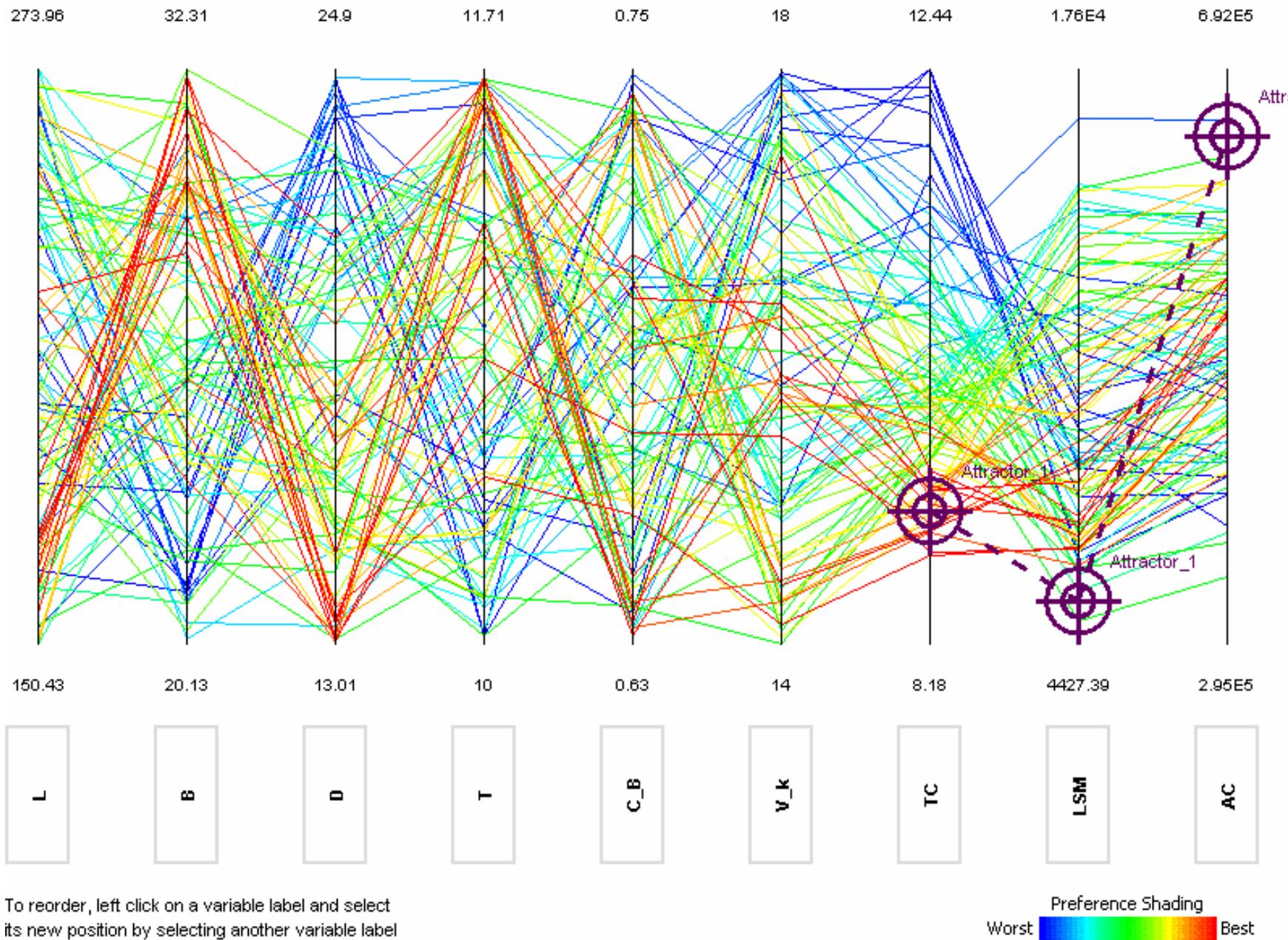
- Minimize:* Transportation Cost
- Minimize:* Light Ship Weight
- Maximize:* Annual Cargo
- subject to:* Nine (9) constraints

* Parsons and Scott (2004)
& Sen and Yang (1998)

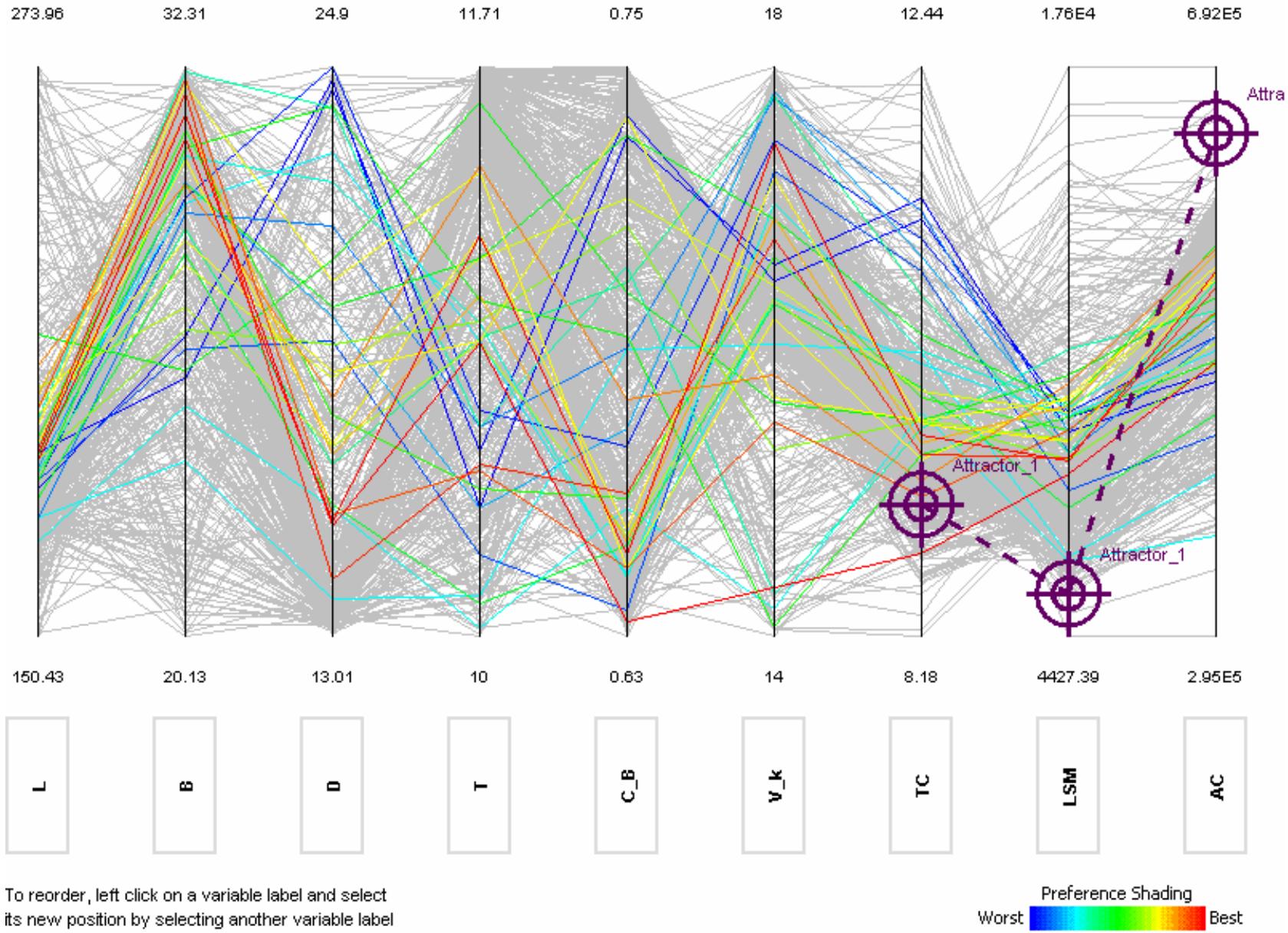
Problem Formulation in ATSV



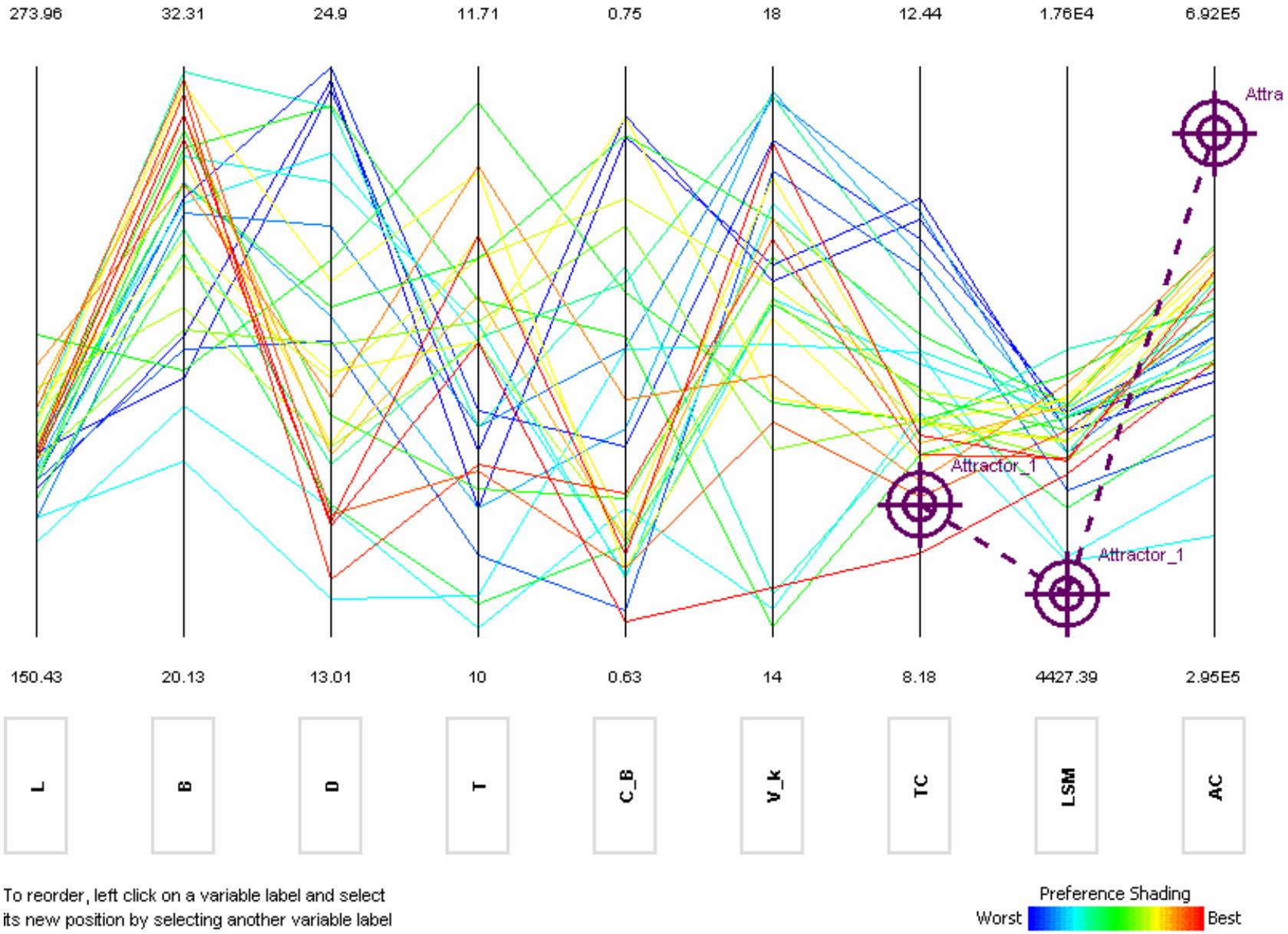
Using Attractors for Three Objectives



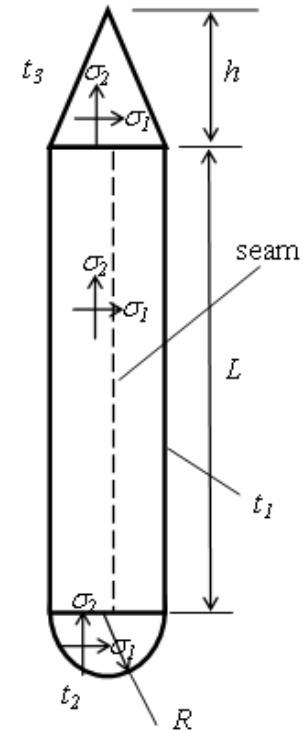
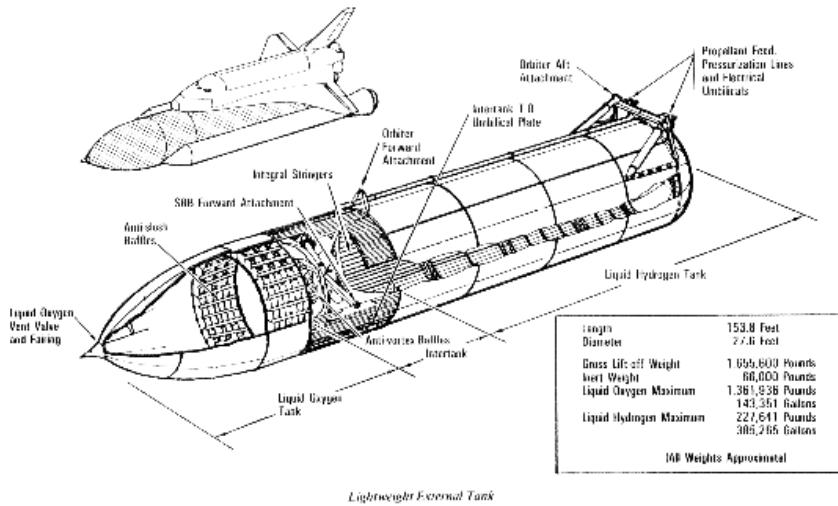
Visualization of Results



Visualization of Results



Space Shuttle External Fuel Tank



Originally developed by Dr. Jaroslaw Sobieski to illustrate how changes in a problem's objective function can influence the resulting optimal design

Minimize: ROI

Subject to: volume, stress, and vibration constraints + bounds:

$$0.01 \leq L_n \leq 5.0$$

$$0.50 \leq R_n \leq 2.0$$

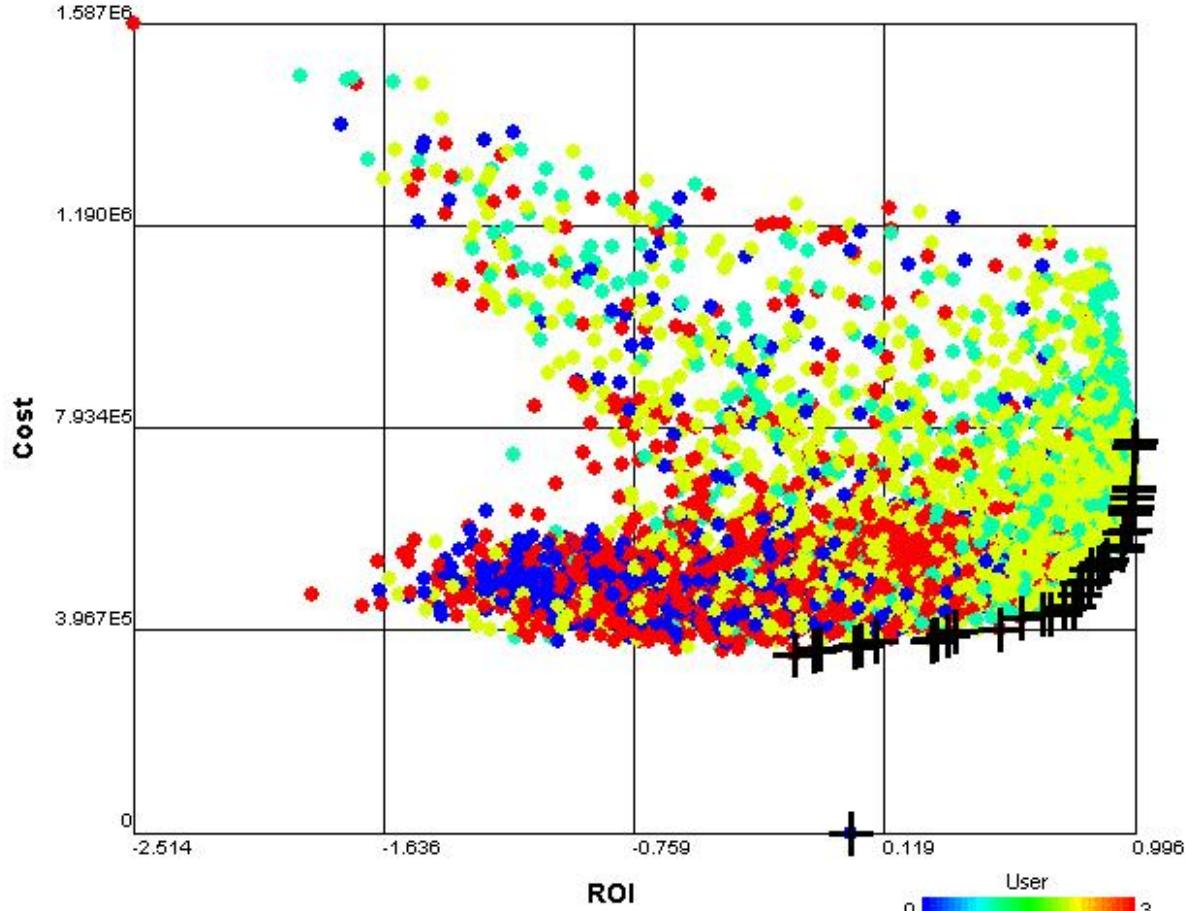
$$0.25 \leq t_{1n} \leq 2.0$$

$$0.25 \leq t_{2n} \leq 2.0$$

$$0.25 \leq t_{3n} \leq 2.0$$

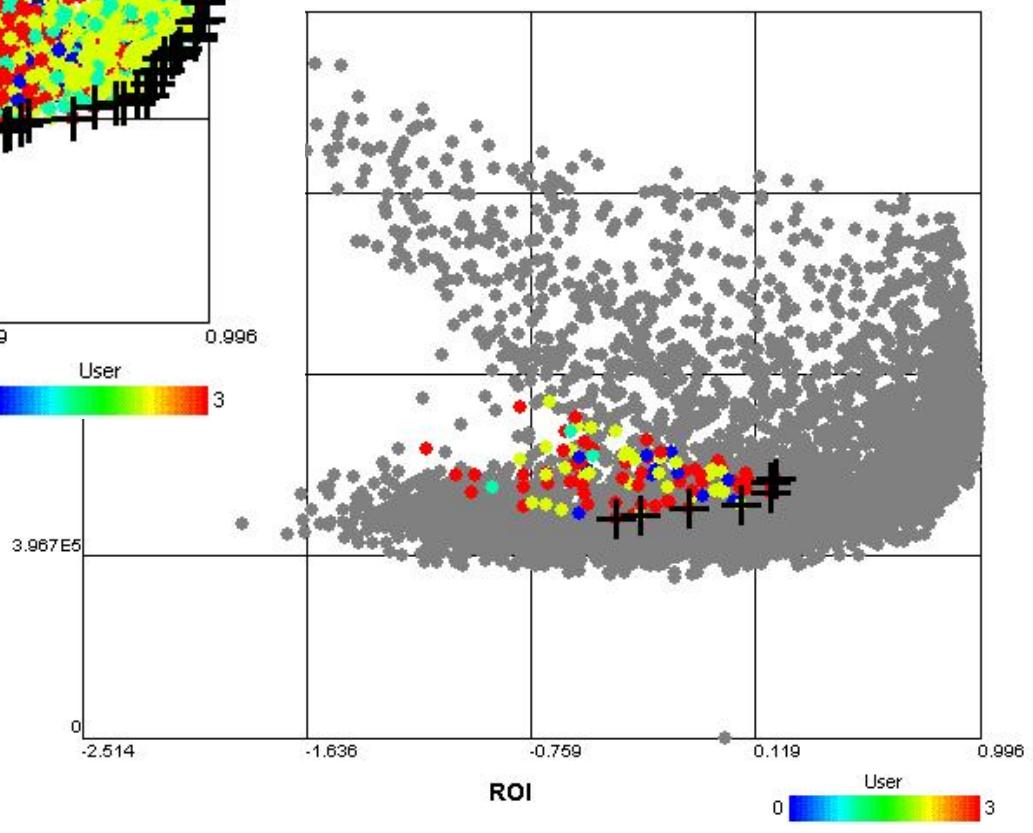
$$0.10 \leq h/R_n \leq 5.0$$

Distributed Collaborative Design Experiments



- Each user steers own portion of the model
 - Colors indicate the designs they explored
 - Gray means infeasible

- Problem divided into:
 - System engineer
 - Cost engineer
 - Structural engineer
 - Aerodynamic engineer



Closing Remarks

- Trade space exploration is a powerful alternative to optimization-based approaches to decision-making
 - Provides a visual and intuitive means to explore trade spaces
- ATSV combines multi-dimensional data visualization and visual steering commands to facilitate the trade space exploration process
- Trade space exploration is a rich arena for research in many areas that have either not been examined or have lain dormant for many years
- Experimental studies are underway to provide empirical evidence of the benefits of putting humans “back-in-the-loop” during design optimization

